

SECTION A (MATHEMATICS 1 AND 2)

A1.

$$\left(\begin{array}{ccc|c} 1 & 1 & 1 & 10 \\ 2 & -1 & 3 & 4 \\ 1 & 0 & 2 & 20 \end{array} \right)$$

$$\left(\begin{array}{ccc|c} 1 & 1 & 1 & 10 \\ 0 & -3 & 1 & -16 \\ 0 & -1 & 1 & 10 \end{array} \right) \quad \begin{array}{l} r_2 - 2r_1 \\ r_3 - r_1 \end{array}$$

$$\left(\begin{array}{ccc|c} 1 & 1 & 1 & 10 \\ 0 & -3 & 1 & -16 \\ 0 & 0 & \frac{2}{3} & 15\frac{1}{3} \end{array} \right) \quad r_3' - \frac{1}{3}r_2'$$

$$z = 23; y = 13; x = -26$$

1 method mark for Gaussian elimination

1 for middle row

1 for bottom row

1 for third row

1 for back substitution

Total 5

A2.

(a) $f(x) = (2+x) \tan^{-1} \sqrt{x-1}$

$$f'(x) = \tan^{-1} \sqrt{x-1} + \frac{(2+x)\frac{1}{2}(x-1)^{-\frac{1}{2}}}{1+(x-1)}$$

$$= \tan^{-1} \sqrt{x-1} + \frac{2+x}{2x\sqrt{x-1}}$$

1 method mark for product rule

1 for first term

1 for second term

1 mark

(b)

$$g(x) = e^{\cot 2x}$$

$$g'(x) = -2 \operatorname{cosec}^2 2x e^{\cot 2x}$$

1 method mark for the chain rule

1E1 for the rest

Total 6

A3.

$$\int_0^{\pi/4} 2x \sin 4x dx$$

$$= \left[2x \int \sin 4x dx - \int \left(2 \int \sin 4x dx \right) dx \right]_0^{\pi/4}$$

$$= \left[2x \frac{1}{4} (-\cos 4x) + \frac{1}{2} \int \cos 4x dx \right]_0^{\pi/4}$$

$$= \left[-\frac{1}{2} x \cos 4x + \frac{1}{8} \sin 4x \right]_0^{\pi/4}$$

$$= -\frac{1}{2} \frac{\pi}{4} (-1) = \frac{\pi}{8}$$

1 method mark for integration by parts

1 for first term

1 for second term

1 for reaching this stage

1E1 for the rest

Total 5

A4.

When $n = 1$, LHS = 2,

RHS = $\frac{1}{2} \times 1 \times 4 = 2$, thus true for $n = 1$.

Assume true for $n = k$ and consider the case when $n = k+1$

$$2 + 5 + 8 + \dots + (3k-1) + (3(k+1)-1)$$

$$= \frac{1}{2} k(3k+1) + 3k + 2$$

$$= \frac{1}{2} (3k^2 + 7k + 4)$$

$$= \frac{1}{2} (k+1)(3k+4)$$

$$= \frac{1}{2} (k+1)(3(k+1)+1)$$

ie since true for $n = k$ implies true for $n = k+1$ and true for $n = 1$, the result is true for all $n \geq 1$.

1 for starting condition

1 for stating the inductive hypothesis

1 for applying the inductive hypothesis

1 for final form

1 for statement

Total 5

A5.

$$(a) \quad \frac{x}{x^2-1} = \frac{A}{x-1} + \frac{B}{x+1}$$

$$= \frac{\frac{1}{2}}{x-1} + \frac{\frac{1}{2}}{x+1}$$

$$(b) \quad \frac{x^3}{x^2-1} = x + \frac{x}{x^2-1}$$

$$= x + \frac{\frac{1}{2}}{x-1} + \frac{\frac{1}{2}}{x+1}$$

$$\int \frac{x^3}{x^2-1} dx = \int x + \frac{\frac{1}{2}}{x-1} + \frac{\frac{1}{2}}{x+1} dx$$

$$= \frac{1}{2}x^2 + \frac{1}{2}\ln(x-1) + \frac{1}{2}\ln(x+1) + c$$

$$= \frac{1}{2}(x^2 + \ln(x^2-1)) + c$$

1 method mark

1 for accuracy

1 for division

1 for applying result of (a)

2E1 for the rest

Total 6

A6.

$$\left(x^2 - \frac{2}{x}\right)^4$$

$$= x^8 - 4x^6 \cdot \frac{2}{x} + 6x^4 \cdot \frac{4}{x^2} - 4x^2 \cdot \frac{8}{x^3} + \frac{16}{x^4}$$

$$= x^8 - 8x^5 + 24x^2 - \frac{32}{x} + \frac{16}{x^4}$$

1 for binomial coefficients
2E1 for accuracy

2E1 for accuracy

Total 5

A7. (a)

$$xy + y^2 = 2$$

$$x \frac{dy}{dx} + y + 2y \frac{dy}{dx} = 0$$

$$(x + 2y) \frac{dy}{dx} = -y$$

$$\frac{dy}{dx} = \frac{-y}{x + 2y}$$

(b)

When $x = 1$ and $y = 1$,

$$\frac{dy}{dx} = \frac{-1}{1+2} = -\frac{1}{3}$$

Equation is $(y - 1) = -\frac{1}{3}(x - 1)$.

1 method mark
1 for accuracy

1E1

1E1

1E1

Total 5

A8.

(a) $f(x) = \frac{x^2 + 6x + 12}{x + 2} = x + 4 + \frac{4}{x + 2}$

(b) Vertical asymptote $x = -2$

Slant asymptote $y = x + 4$

(c) $f'(x) = 1 - \frac{4}{(x + 2)^2} = 0$ at S.V.

$$(x + 2)^2 = 4$$

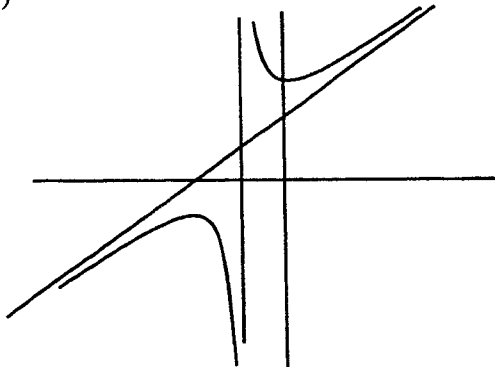
$$x + 2 = \pm 2$$

$$x = 0 \text{ or } x = -4.$$

$$f''(x) = \frac{8}{(x + 2)^3}$$

When $x = 0, f(0) = 6$ and $f''(0) > 0$ so $(0, 6)$ is a minimum turning point. When $x = -4, f(-4) = -2$ and $f''(-4) < 0$ so $(-4, -2)$ is a maximum turning point

(d)



(e) $-2 < k < 6$

2E1

1 for vertical asymptote

1 for slant asymptote

1 for derivative

1 for coordinates

1 for nature

1 for y coordinates

1 mark

1 mark

Total 10

A9. (a) $-1 = \cos \pi + i \sin \pi$

(b) Let $z = \cos \theta + i \sin \theta$, then

$$z^3 \cos 3\theta + i \sin 3\theta$$

$$\cos 3\theta = -1 \Rightarrow 3\theta = \pi \text{ or } 3\pi \text{ or } 5\pi$$

$$\Rightarrow \theta = \frac{\pi}{3} \text{ or } \pi \text{ or } \frac{5\pi}{3}$$

The roots are

$$\cos \frac{\pi}{3} + i \sin \frac{\pi}{3} = \frac{1}{2}(1 + i\sqrt{3})$$

$$\cos 3\pi + i \sin 3\pi = -1$$

$$\cos \frac{5\pi}{3} + i \sin \frac{5\pi}{3} = \frac{1}{2}(1 - i\sqrt{3})$$

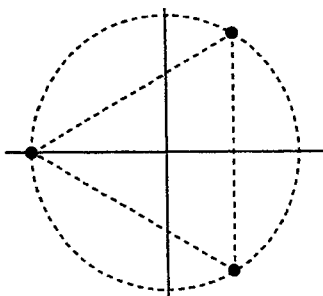
$$\left[\frac{1}{2}(1 + i\sqrt{3})^2 \right] = \frac{1}{4}(1 + 2i\sqrt{3} - 3)$$

$$= -\frac{1}{2}(1 - i\sqrt{3})$$

$$\left[\frac{1}{2}(1 - i\sqrt{3})^2 \right] = \frac{1}{4}(1 - 2i\sqrt{3} - 3)$$

$$= -\frac{1}{2}(1 + i\sqrt{3})$$

(c)



The points are on the unit circle and are equally spaced.

OR

The solutions form an equilateral triangle.

1 mark

1 for applying de Moivre

2E1 for the values of θ

2E1 for the roots

1 mark

1 mark

1 for diagram

1 mark

1 mark

OR

2 marks

Total 11

A10. (a) $\frac{dM}{dt} = kM$

$$\int \frac{dM}{M} = \int k dt$$

$$\ln M = kt + c$$

$$t = 0, M = M_0 \Rightarrow c = \ln M_0$$

$$M = M_0 e^{kt}$$

1 method

1 mark

1 mark

(b) When $t = 30$, $M = \frac{1}{2} M_0$ so

$$e^{30k} = 0.5$$

$$k = \frac{1}{30} \ln 0.5 \approx -0.0231$$

1 mark

1 mark

1 mark

(c) When $t = 35$

$$\frac{M}{M_0} = e^{35k} \approx 0.4454 \approx 45\%$$

2E1

(d) When $\frac{M}{M_0} = 0.25$

$$e^{kt} = 0.25$$

$$t = \frac{1}{k} \ln 0.25 = \frac{30 \ln 0.25}{\ln 0.5} = 60$$

1 mark

1 mark

The manufacturer is justified.

Total 10

SECTION B (MATHEMATICS 3)

B1.

$$149 = 1 \times 139 + 10$$

$$139 = 13 \times 10 + 9$$

$$10 = 1 \times 9 + 1$$

$$1 = 10 - 9$$

$$= 10 - (139 - 13 \times 10)$$

$$= 14 \times (149 - 139) - 139$$

$$= 14 \times 149 - 15 \times 139$$

ie $x = 14$ and $y = -15$.

1 method

2E1 accuracy

1 mark

Total 4

B2.

$$\frac{dy}{dx} + \frac{y}{x} = x$$

Integrating factor is $e^{\int \frac{1}{x} dx} = e^{\ln x} = x$

$$\therefore x \frac{dy}{dx} + y = x^2$$

$$\frac{d}{dx}(xy) = x^2$$

$$\text{Hence } xy = \int x^2 dx = \frac{1}{3}x^3 + c$$

$$\text{Thus } y = \frac{1}{3}x^2 + \frac{c}{x}.$$

1 method

1 accuracy

1 mark

1 mark

Total 4

B3.

$$AB = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \\ 1 & -1 & -1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 1 \\ 4 & -2 & -2 \\ -3 & 2 & 1 \end{pmatrix}$$
$$= \begin{pmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{pmatrix} = 2I$$

$$A^{-1} = \frac{1}{2}B$$

$$= \frac{1}{2} \begin{pmatrix} 1 & 0 & 1 \\ 4 & -2 & -2 \\ -3 & 2 & 1 \end{pmatrix}$$

$$A^2B = A \cdot AB = A \cdot 2I = 2A$$

$$= \begin{pmatrix} 2 & 2 & 2 \\ 2 & 4 & 6 \\ 2 & -2 & -2 \end{pmatrix}$$

1 mark

1 mark

1 mark

1 mark

Total 4

B4.

Let $f(x) = (x+2) \ln(2+x)$

then $f(0) = 1 + \ln 2$

$$f'(x) = 1 + \ln(x+2) \quad f'(0) = 1 + \ln 2$$

$$f''(x) = (x+2)^{-1} \quad f''(0) = \frac{1}{2}$$

$$f'''(x) = -(x+2)^{-2} \quad f'''(0) = -\frac{1}{4}$$
$$(x+2) \ln(2+x)$$

$$= 2 \ln 2 + (1 + \ln 2)x + \frac{1}{2} \frac{x^2}{2!} - \frac{1}{4} \frac{x^3}{3!} + \dots$$

$$= 2 \ln 2 + (1 + \ln 2)x + \frac{x^2}{4} - \frac{x^3}{24} + \dots$$

1 mark

1 for derivatives

1 for evaluating derivatives

1 mark

Total 4

B5.

$$\frac{d^2y}{dx^2} + 2\frac{dy}{dx} - 3y = 6x - 1$$

$$AE \ m^2 + 2m - 3 = 0$$

$$\Rightarrow m = 1 \text{ or } m = -3$$

$$\text{Complementary function } y = Ae^x + Be^{-3x}$$

$$\text{Particular integral } y = ax + b$$

$$\frac{dy}{dx} = a; \frac{d^2y}{dx^2} = 0$$

$$0 + 2a - 3ax - 3b = 6x - 1$$

$$a = -2; b = -1$$

General solution

$$y = Ae^x + Be^{-3x} - 2x - 1$$

1 for auxiliary equation

1 for the roots

1 for complementary function

1 for trial integral

1 for values

Total 5

B6.

(a) (i)

In parametric form, L_2 can be written as

$$x = -2s; y = -2 - s; z = 9 + 2s$$

Solving x and y

$$8 - 2t = -2s \quad \Rightarrow s = t - 4$$

$$-4 + 2t = -2 - s \quad s = 2 - 2t$$

$$t - 4 = 2 - 2t \Rightarrow t = 2 \text{ and } s = -2$$

from L_1 , $z = 3 + t = 5$. From L_2 ,

$$z = 9 + 2s = 9 - 4 = 5.$$

So the lines intersect and do so at $(4, 0, 5)$.

(ii) Representing an angle between

L_1 and L_2 by θ

$$\cos \theta = \frac{(-2)^2 + 2(-1) + 1(2)}{\sqrt{2^2 + 2^2 + 1^2} \sqrt{2^2 + 1^2 + 2^2}} = \frac{4}{9}$$

(b) (i) Direction of L_2 is $-2i - j + 2k$.

Equation of Π is of the form

$$-2x - y + 2z = k.$$

Using $(1, -4, 2)$ gives

$$k = -2 + 4 + 4 = 6 \text{ so an equation is}$$

$$-2x - y + 2z = 6.$$

(ii) Substituting

$$x = 8 - 2t, y = -4 + 2t, z = 3 + t \text{ into}$$

Π gives

$$-16 + 4t + 4 - 2t + 6 + 2t = 6$$

$$4t = 12$$

$$t = 3$$

The point of intersection is $(2, 2, 6)$.

1 for parametric form

3E1 for working out the point of intersection

1 for method

1 for correct calculation

1 for direction vector

1 for equation

1 for final equation

1 for parameter

1 for point

Total 11

	Mark
<p>C4.</p> $p = \frac{320}{400} = 0.8$ <p>As 95% confidence interval for the population proportion is given by:-</p> $p \pm 1.96 \sqrt{\frac{p(1-p)}{n}}$ $= 0.8 \pm 1.96 \sqrt{\frac{0.8 \times 0.2}{400}}$ $= 0.8 \pm 0.04$ $= 0.76, 0.84$ <p>Since the confidence interval does not include 0.9 the claim made by the action group is not supported by the data.</p>	5
<p>C5.</p> $\bar{x} = 157.5$ $z = \frac{\frac{\bar{x} - \mu}{\frac{\sigma}{\sqrt{n}}}}{\frac{6}{\sqrt{36}}} = \frac{157.5 - 160}{6} = -2.5$ <p>The critical region for testing H_0 :</p> <p>$\mu = 160$ against $H_1 : \mu < 160$</p> <p>is $z < -1.64$.</p> <p>Since $-2.5 < -1.64$ the null hypothesis would be rejected</p>	5

	Mark
C6.	
(a) (i) $P(X \geq 3) = 1 - F(2) = 1 - 0.6767 = 0.3233$	2
(ii) $P(X = 3) = F(3) - F(2) = 0.8571 - 0.6767 = 0.1804$	2
(iii) $P(Y = 0) = F(0) = 0.0498$	1
(b) The total number of calls will have the Poisson distribution with parameter $2+3=5$.	2
(c) $P(T > 5) = 1 - F(4) = 1 - 0.4405 = 0.5595$	2

SECTION D (NUMERICAL ANALYSIS 1)

D1. $f(x) = e^{1-2x}$ $f'(x) = -2e^{1-2x}$ $f''(x) = 4e^{1-2x}$ $f'''(x) = -8e^{1-2x}$

Taylor polynomial is $p(x) = p(1+h) = e^{-1} - 2e^{-1}h + 2e^{-1}h^2 - 4/3e^{-1}h^3$ 3

For $f(0.98)$, $h = -0.02$; $p(0.98) = e^{-1}(1 - 2(-0.02) + 2(-0.02)^2)$
 $= e^{-1}(1 + 0.04 + 0.0008) = 0.3829$ 2

Principal truncation error term is $-4/3 e^{-1} h^3 = 3.9 \times 10^{-6}$
Hence second order estimate should be accurate to 4D. 2

D2.

$$L(2.5) = \frac{(2.5-3)(2.5-4)}{(-2)(-3)} 1.7831 + \frac{(2.5-1)(2.5-4)}{(2)(-1)} 2.0226 + \frac{(2.5-1)(2.5-3)}{(3)(1)} 1.9308$$

$$= 1.7831/8 + 9 \times 2.0226/8 - 1.9308/4 = 2.016$$
 3

D3.

$$\Delta^2 f_0 = \Delta f_1 - \Delta f_0 = (f_2 - f_1) - (f_1 - f_0) = f_2 - 2f_1 + f_0$$

$$\Delta^3 f_0 = (f_3 - 2f_2 + f_1) - (f_2 - 2f_1 + f_0) = f_3 - 3f_2 + 3f_1 - f_0$$
 2

Maximum error is $\epsilon + 3\epsilon + 3\epsilon + \epsilon = 8\epsilon$ 1

D4.

Difference table is:

i	x	f(x)	diff1	diff2	diff3
0	0.5	-0.623	471	136	24
1	0.6	-0.152	607	160	27
2	0.7	0.455	767	187	23
3	0.8	1.222	954	210	
4	0.9	2.176	1164		
5	1.0	3.340			

3

$$\Delta^3 f_1 = 0.027$$

1

$$p = 0.3$$

$$\begin{aligned} f(0.574) &= -0.152 + 0.3(0.607) + \frac{(0.3)(-0.7)}{2}(0.160) + \frac{(0.3)(-0.7)(-1.7)}{6}(0.027) \\ &= -0.152 + 0.182 - 0.017 + 0.002 \\ &= 0.015 \end{aligned}$$

3

D5. Consider fitting $y = Ax^2 + Bx + C$ through $(-h, y_0)$, $(0, y_1)$ and (h, y_2) .

$$\text{Then } y_0 = Ah^2 - Bh + C$$

$$y_1 = C \qquad y_0 + y_2(Ah^2 + C)$$

$$y_2 = Ah^2 + Bh + C$$

$$\begin{aligned} \text{Approximation to } \int_{-h}^h f(x) dx \text{ is: } \int_{-h}^h (Ax^2 + Bx + C) dx &= \left[\frac{Ax^3}{3} + \frac{Bx^2}{2} + Cx \right]_{-h}^h \\ &= 2(Ah^3/3 + Ch) = h\{2(Ah^2 + C) + 4C\}/3 \\ &= h(y_0 + 4y_1 + y_2)/3 \end{aligned}$$

4

$f^{(4)}(0) = -12$ which gives maximum numeric value of $f^{(4)}(x)$ on interval since $f^{(4)}(1) = 0.79$.

$$\text{Then } |E| = 0.125^4 \times 12/180 = 0.00016$$

Hence $I_8 = 0.2391$ is a suitable estimate.

4

Richardson extrapolation gives

$$I = (16 \times 0.2391235 - 0.2389685)/15 = 0.2391338$$

2

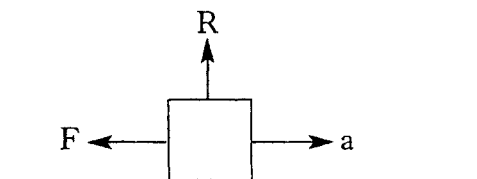
The principal truncation term is now in h^6 giving a likely reduction of the order of 0.125^2 , ie two orders of magnitude.

Hence estimate would be 0.239134

2

SECTION E (MECHANICS 1)

E1.



Using $v^2 = u^2 + 2as$ with $(u = 0.2, v = 0, s = 1)$ the deceleration is

$$a = -\frac{u^2}{2s} = -0.02 \text{ms}^{-2}.$$

The reaction force is $R = mg$ and the frictional force $F = \mu mg$ in the usual notation. By Newton II

$$ma = -\mu mg$$

$$\Rightarrow \mu = -\frac{a}{g} = 0.002$$

(1 mark)

(1 mark)

(1 mark)

(1 mark)

E2. (a) Here $v = 2t(1 - 3t) + 1 = -6t^2 + 2t + 1$ so

$$a = 0 \Leftrightarrow \frac{dv}{dt} = 0 \Leftrightarrow -12t + 2 = 0 \Leftrightarrow t = \frac{1}{6}$$

(1 mark)

(b) Noting that $\frac{dx}{dt} = v$

$$x = t^2 - 2t^3 + t + c$$

and with $x(0) = 0$ then $c = 0$.

(1 mark)

The particle is at the origin when

$$x = 0 \Leftrightarrow t(2t + 1)(t - 1) = 0 \Leftrightarrow t = 0, -\frac{1}{2}, 1$$

(1 mark)

When the particle returns to the origin when $t > 0$ so we must have $t = 1$.

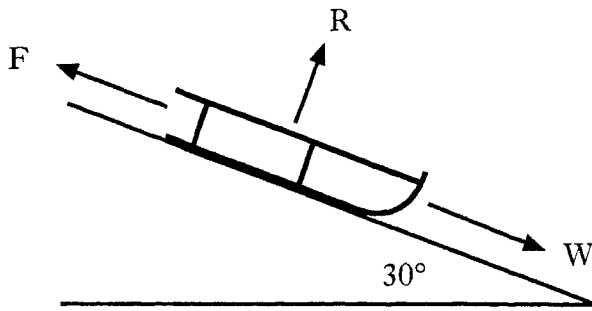
(1 mark)

At $t = 1$ the acceleration is $a = -10 \text{ms}^{-2}$.

(1 mark)

E3.

(a)



The reaction force is $R = mg \cos 30 = \frac{\sqrt{3}}{2} mg$, where m is the combined mass of John and the sledge.

The frictional force is $F = \frac{\sqrt{3}}{2} \mu mg$.

The component of weight down the hillside is

$$W = mg \sin 30 = \frac{1}{2} mg$$

By Newton II

$$ma = W - F$$

$$\Rightarrow a = \frac{1}{2}(1 - \sqrt{3}\mu)g$$

(b) If $\mu > \frac{1}{\sqrt{3}}$ then $1 - \sqrt{3}\mu < 0$,

which implies that the sledge decelerates on the lower part of the hill.

(1 mark for resolving perp to plane)

(1 mark)

(1 mark)

(1 mark)

(1 mark)

(1 mark)

E4. The velocity of the wind (relative to the ground) is

$\underline{v}_w = u\underline{i} + v\underline{j}$ where \underline{i} is the unit vector in the easterly direction, \underline{j} the unit vector in the northerly direction.

Joan has velocity $\underline{v}_j = 20\underline{j}$ and the velocity of the wind relative to Joan is

$$\underline{v}_w - \underline{v}_j = u\underline{i} + (v - 20)\underline{j}$$

Since the wind appears to come from the east, $v = 20$.

If Joan is cycling at 30 km/hr, $\underline{v}_j = 30\underline{j}$, and

$$\underline{v}_w - \underline{v}_j = u\underline{i} - 10\underline{j}$$

Since the wind appears to come from the north-east, $u = -10$.

The wind speed is

$$|\underline{v}_w| = \sqrt{100 + 400} \approx 22.4 \text{ km/hr}$$

By trig the wind direction is 26.6° west of north.

(1 mark)

(1 mark)

(1 mark)

(1 mark)

(1 mark)

(1 mark)

E5.

(a) From the equations of motion the position of the particle at time t is

$$\ddot{x} = 0 \quad \dot{x} = V \cos \alpha \Rightarrow x = (V \cos \alpha)t,$$

and

$$\ddot{y} = -g$$

$$\Rightarrow \dot{y} = gt + V \sin \alpha$$

$$\Rightarrow y = (V \sin \alpha)t - \frac{1}{2}gt^2.$$

(1 mark)

(1 mark)

Setting $y = 0$ gives the time of flight to be

$$t = \frac{2V \sin \alpha}{g},$$

(1 mark)

and the range

$$R = \frac{V^2}{g}(2 \sin \alpha \cos \alpha) = \frac{V^2}{g} \sin 2\alpha.$$

(1 mark)

(b)(i) Using (a) with $\alpha = 15^\circ$ gives

$$D - d = \frac{V^2}{2g} \quad (*)$$

and when $\alpha = 30^\circ$

$$D + d = \frac{\sqrt{3}V^2}{2g} \quad (**)$$

(1 mark)

Eliminating the velocity between (*) and (**) gives

$$D - d = \frac{1}{\sqrt{3}}(D + d)$$

(1 mark)

which rearranges to give

$$d = \left(\frac{\sqrt{3} - 1}{\sqrt{3} + 1} \right) D.$$

(1 mark)

From equation (*)

$$V^2 = 2gD \left(1 - \left(\frac{\sqrt{3} - 1}{\sqrt{3} + 1} \right) \right)$$

(1 mark)

and simplifying

$$V^2 = \frac{4gD}{\sqrt{3} + 1}.$$

(1 mark)

(ii) If θ is the required angle of projection, then from (a)

$$\sin 2\theta = \frac{Dg}{V^2} = \frac{1 + \sqrt{3}}{4}$$

(1 mark)

and hence $\theta = 21.5^\circ$ and 68.5° .

(1 mark)

[END OF MARKING INSTRUCTIONS]